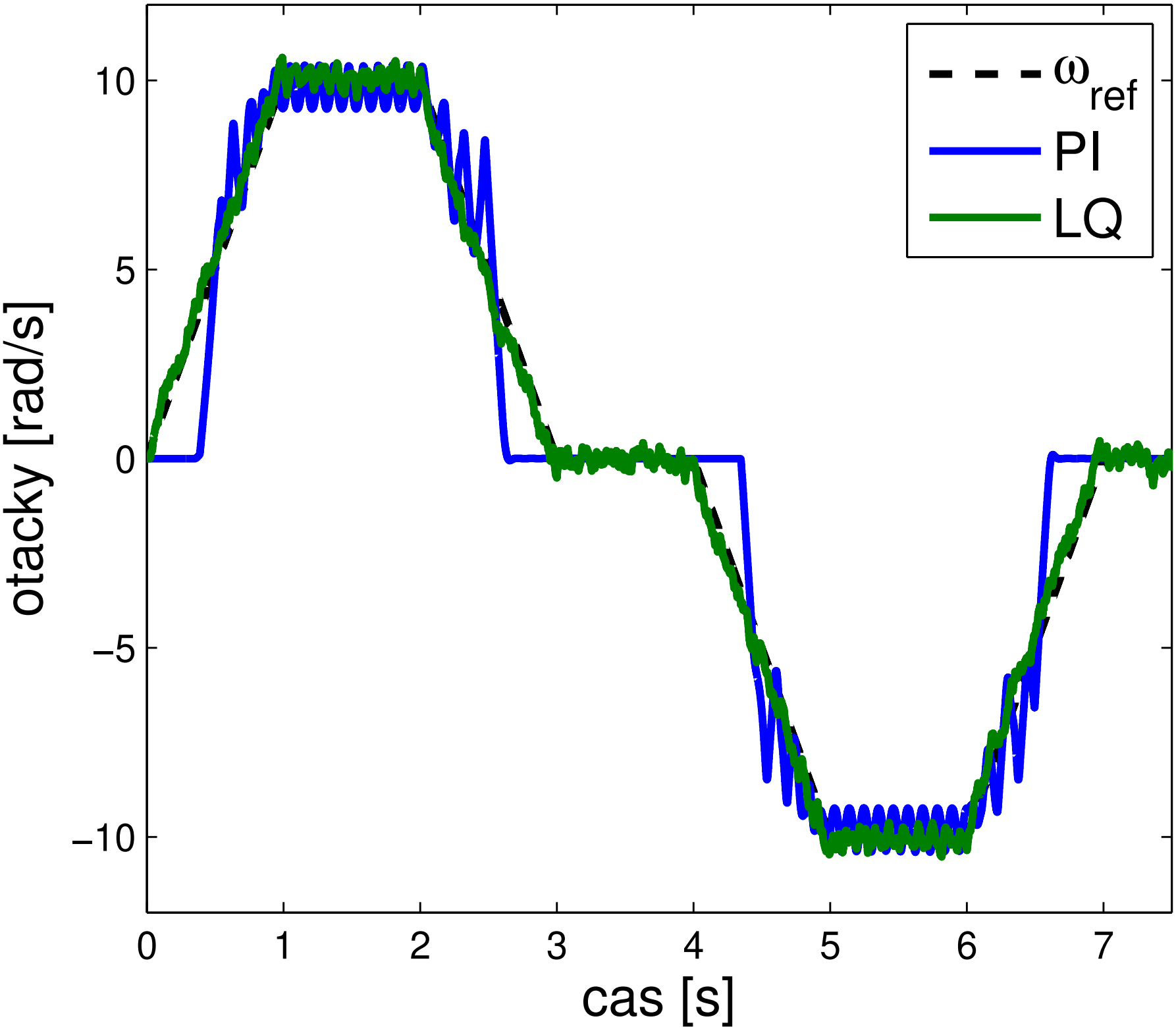
ω_ref
PI
LQ
otacky [rad/s]
cas [s]
10
5
0
−5
−10
0
1
2
3
4
5
6
7