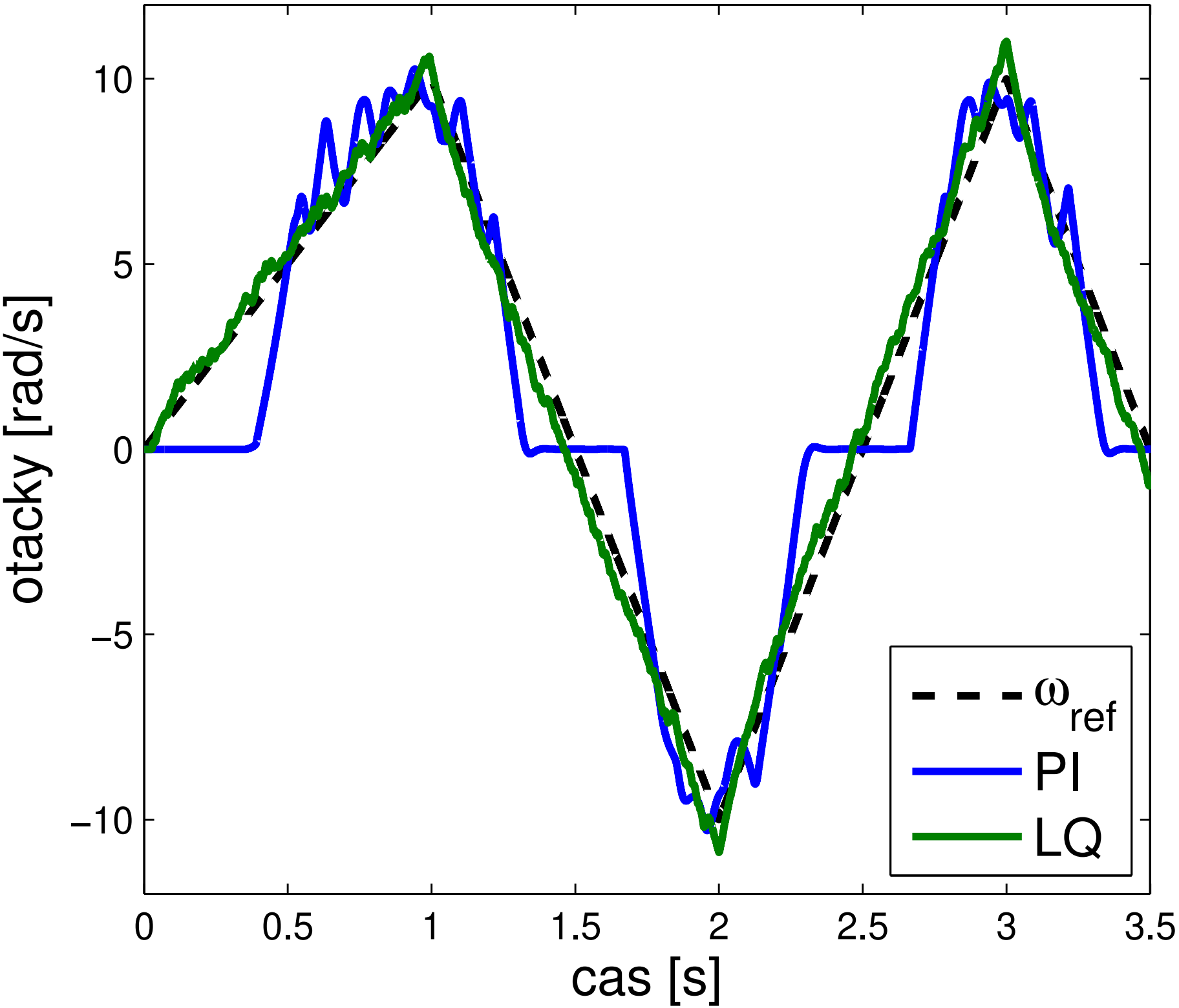
10
5
0
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1
1.5
2
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3
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otacky [rad/s]
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ω_ref
PI
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